

<b>INFORMATION DISCLOSURE STATEMENT BY APPLICANT</b> (Not for submission under 37 CFR 1.99)	<b>Application Number</b>		10597673
	<b>Filing Date</b>		2006-06-03
	<b>First Named Inventor</b>	Moshe Shoham	
	<b>Art Unit</b>	N/A	
	<b>Examiner Name</b>	Not Yet Assigned	
<b>Attorney Docket Number</b>		20763/0205292-US0	

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	2	J-P. Merlet, "Singular configurations of parallel manipulators and Grassmann geometry", Int. J. of Robotics Research, vol 8, no 5, pp 45-56 (1989)	<input type="checkbox"/>
	3	J-P. Merlet, "Determination of the presence of singularities in a workspace volume of a parallel manipulator," NATO-ASI, Computational methods in mechanism.	<input type="checkbox"/>
	4	C. Gosselin et al., "Singularity analysis of closed-loop kinematic chains", IEEE Transactions on Robotics and Automation, vol 6, no 3 (1990)	<input type="checkbox"/>
	5	R. Ben-Horin, "Design Parameters of Parallel Manipulators," The Technion, Israel (1998)	<input type="checkbox"/>
	6	H. Bamberger et al., "Kinematic structure of a parallel robot for MEMS fabrication," Advances in Robot Kinematics, ARK, Italy (2004)	<input type="checkbox"/>
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Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

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- ☐ See attached certification statement.
- ☐ Fee set forth in 37 CFR 1.17 (p) has been submitted herewith.
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A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature	/Marie Collazo/	Date (YYYY-MM-DD)	2007-02-23
Name/Print	Marie Collazo	Registration Number	44085

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